

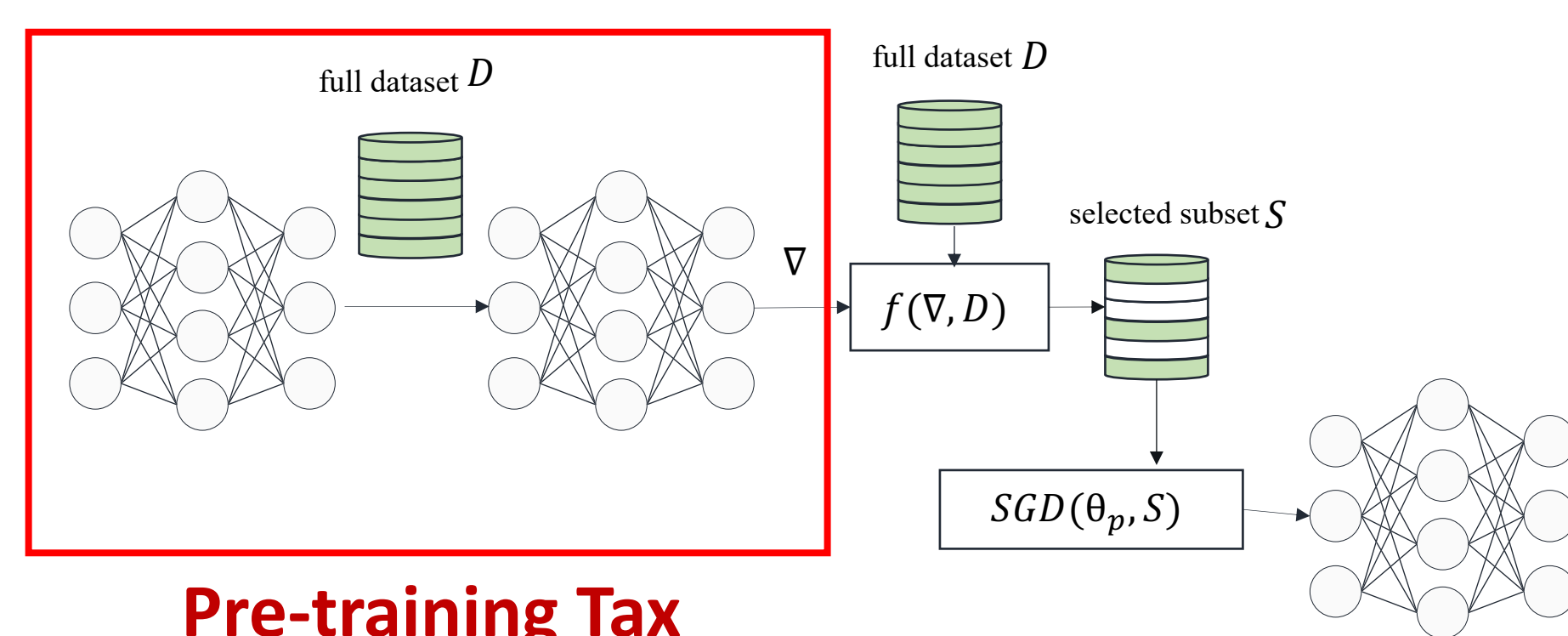
Summary

- We propose a distributed pre-training framework that minimizes the pre-training overhead in subset training.
- We leverage model-soup-inspired ensembling at *initialization* with aggressive augmentation and data-based sparsity to efficiently provide stable and robust gradients for subset selection algorithms.

Gradient-based Subset Training

- With the emergence of billion-parameter-scale models, dataset sizes have also increased accordingly.
- To accelerate training with large-scale datasets, subset training got attention. Using a carefully selected subset, we can train faster without compromising accuracy.
- Recently proposed subset selection algorithms use the initial gradient after pretraining as input to the algorithms.

Pre-training Tax

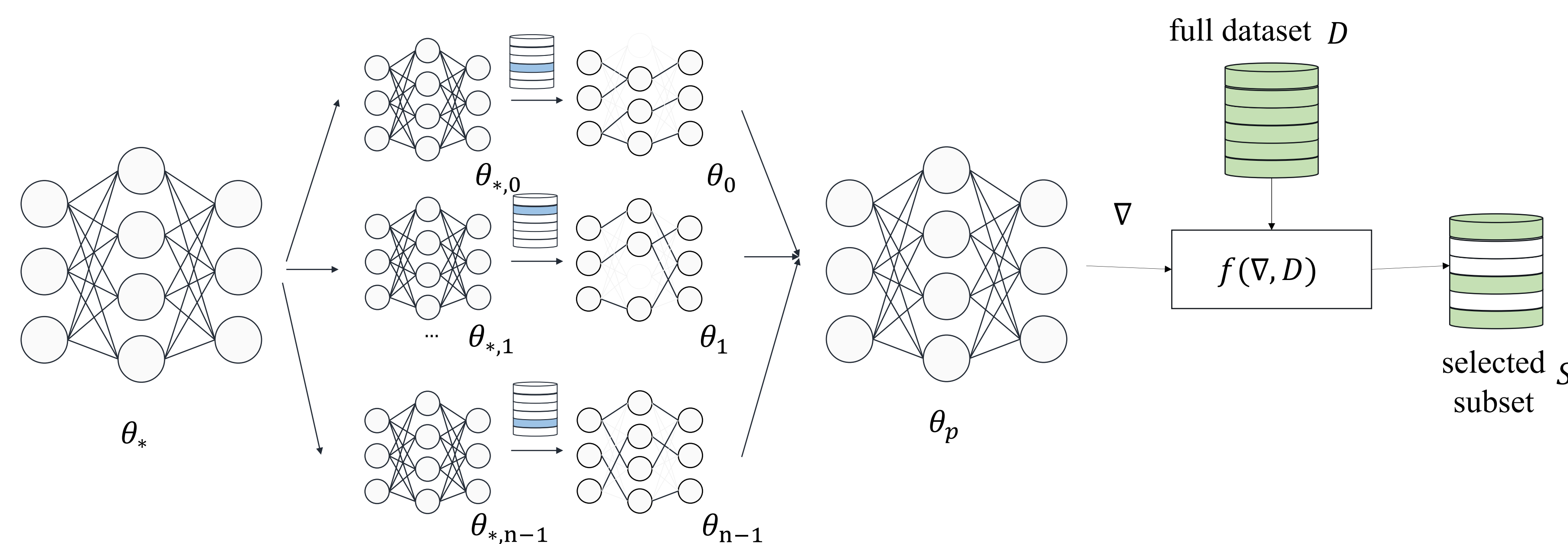


- To get stable and robust gradients, there is a pre-training process with a full dataset, which has non-negligible overhead.
- In prior works, it took 15-40 epochs, which corresponds to 20%-40% of the end-to-end training time.
- We define this pre-training overhead as a **pre-training tax** and aim to reduce the pre-training tax in a principled, scalable, and resource-efficient manner.

Our Method

- To make it scalable so it can run in a distributed environment with minimal communication costs. To do that, in our design,
 - Workers do not synchronize nor communicate during the pre-training.
 - We do not ship the full dataset to each worker to reduce communication costs and local training costs at each worker.
- To meet the quality of the pre-trained model, we provide robust and reliable initial gradients for subset selection algorithms.

Our Method



- Starting from θ_* , we distribute the initial model to different workers with their own random subset that does not overlap each other.
- Each worker do local training with its own set while not communicating with other workers. This can be run in parallel as our workers don't need any synchronization.
- Once local training is done, all models $(\theta_0, \theta_1, \dots, \theta_{n-1})$ are aggregated with *model averaging*.
- Data Augmentation
 - Since we are using very limited samples for local training, we leverage *random augmentation with stronger magnitude*, to mitigate overfitting (14 policies, with magnitude 9).
- Sparsity
 - We apply data-based sparsity as a regularizer to reduce overfitting while increasing model heterogeneity. We use one-shot magnitude pruning due to its simplicity and low overhead.

Experiments

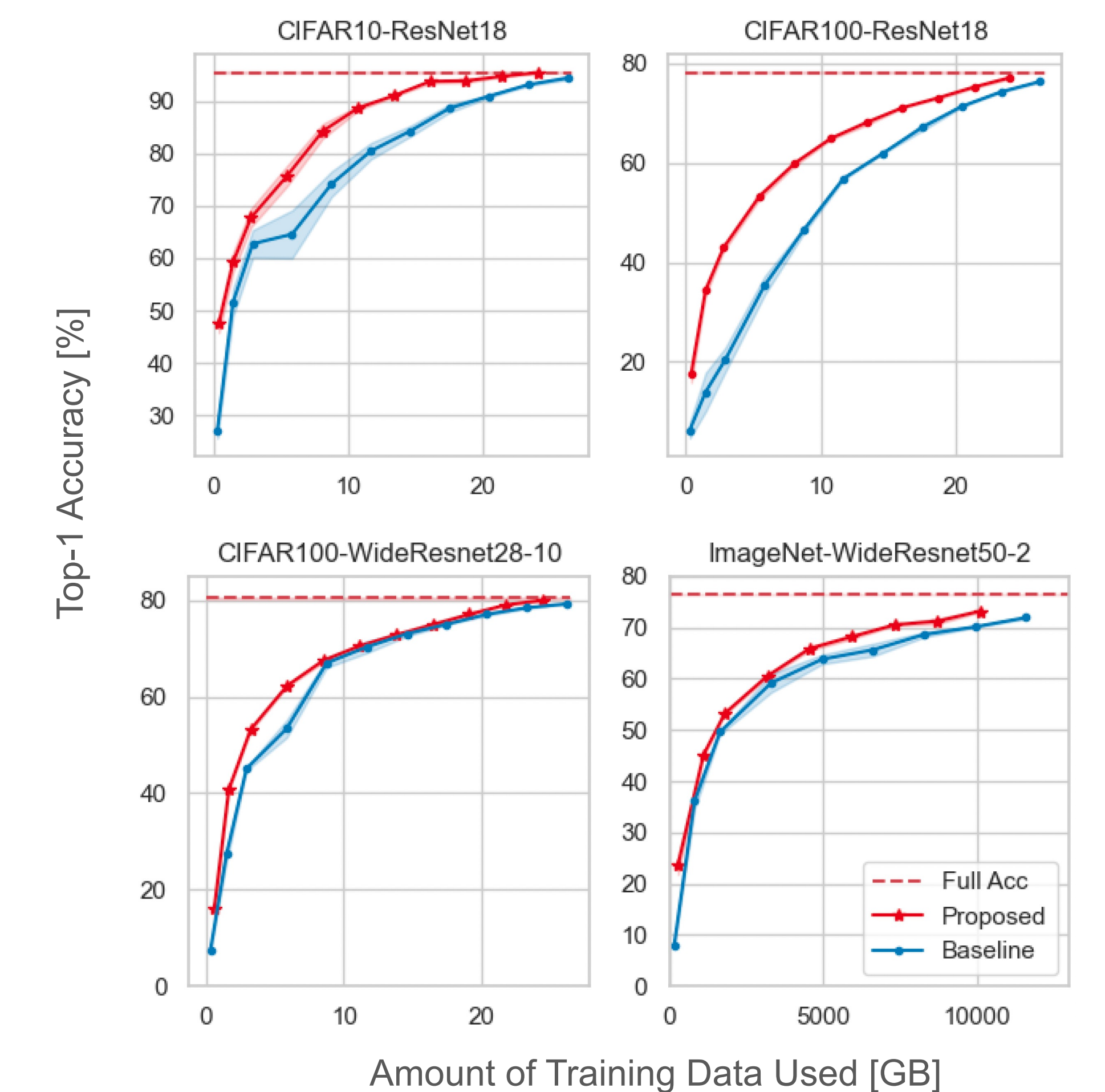
Ablation Study

METHOD	LOW FRACTION (10%)				HIGH FRACTION (70%)			
	RESNET18 CIFAR10	RESNET18 IMAGENET	WRN28-10 CIFAR100	WRN50-2 IMAGENET	RESNET18 CIFAR10	RESNET18 IMAGENET	WRN28-10 CIFAR100	WRN50-2 IMAGENET
FULL ACC	95.4	67.7	80.4	76.5	95.4	67.7	80.4	76.5
①	60.7±5.1	45.0±0.2	38.6±1.0	47.5±0.7	90.5±0.5	63.9±0.2	73.3±0.6	72.0±0.1
① + ②	62.2±3.6	45.2±0.2	38.7±0.9	48.2±0.5	90.7±0.5	64.1±0.1	73.9±0.3	72.4±0.1
① + ③	66.3±2.1	46.2±0.1	43.9±0.4	48.9±0.1	92.6±0.4	64.6±0.0	75.2±0.1	73.1±0.0
① + ② + ③	68.5±1.1	46.4±0.2	45.1±0.3	49.4±0.2	93.6±0.3	64.7±0.1	76.4±0.5	73.3±0.0

① MODEL MERGING ② MODEL PRUNING ③ DATA AUGMENTATION

Experiments

Top-1 Accuracy vs. Amount of data used for the training



Low Fraction Data Improvement

Data Fraction	Glister	This work	Improvement
1%	27.04±1.3	47.50±1.7	+20.45%
5%	51.64±2.7	59.30±1.9	+7.66%
10%	62.75±2.6	67.74±1.8	+4.99%
20%	64.58±4.6	75.65±1.9	+11.07%

End-to-end Speed Up

- 2.8x speedup in end-to-end training.
- 15x reduction in pre-training time.
- Compared to full training dataset, we reduced 87% while not compromising the accuracy.

Model Merging Method

DATA FRACTION	10%	20%	30%	40%	50%
PROPOSED MERGING, ALL	68.05%	78.53%	85.76%	87.74%	89.92%
PROPOSED MERGING, GREEDY	69.50%	79.39%	88.70%	89.25%	91.18%

Model Pruning Method

DATA FRACTION	10%	20%	30%	40%	50%
SNIP	63.76%	69.48%	78.25%	83.02%	86.76%
RANDOM PRUNING	62.51%	72.81%	78.62%	83.13%	87.13%
MAGNITUDE-BASED	66.01%	77.62%	84.21%	86.59%	88.65%